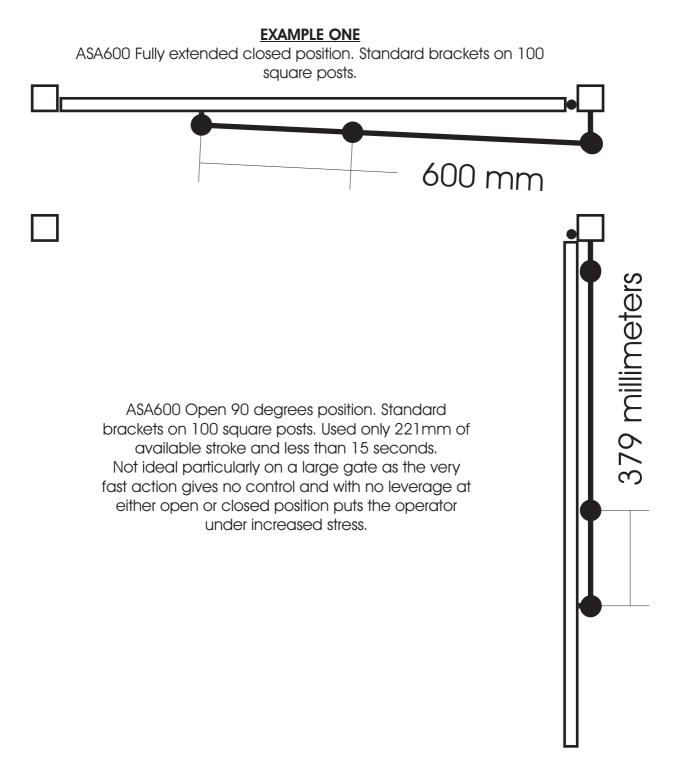


This document is designed to be viewed as three pages. When each page is studied it demonstrates the relationship between bracket positioning and speed and control over a linear operator. Whilst we have used a specific motor here the same theory applies to all linear operators. The dimensions used here are for demonstration only and may not necessarily work well with any particular operator.

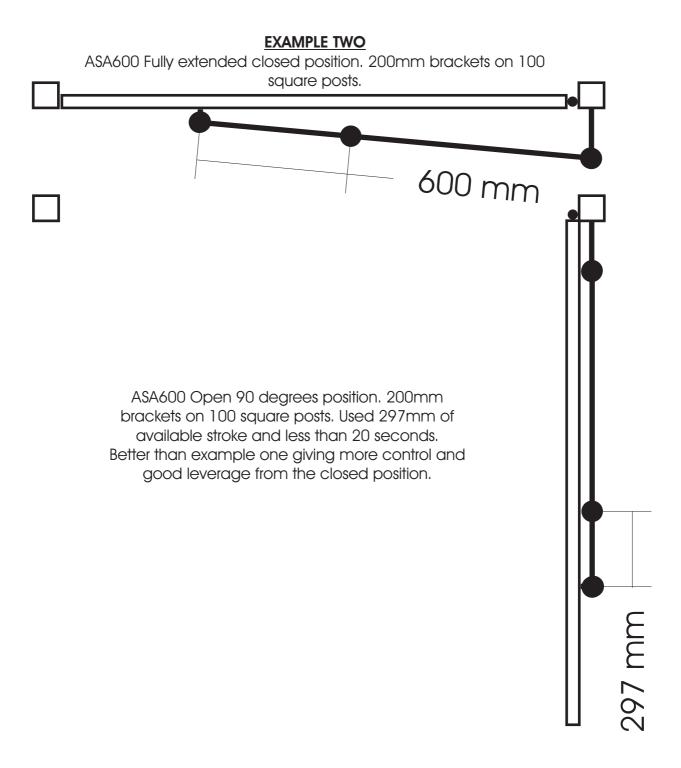
Remember that if you have difficulty swinging the gate with your operator in manual override mode then what chance does the motor have. Adjust your settings a little at a time until you get the desired setting.





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