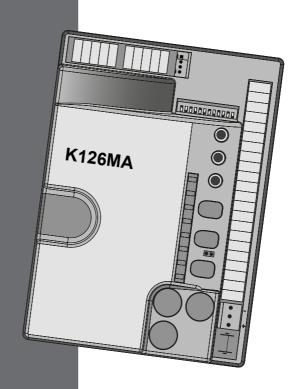


GUIDA ALL'INSTALLAZIONE

INSTALLATION GUIDE INSTALLATIONSANLEITUNG NOTICE D'INSTALLATION GUÍA PARA LA INSTALACIÓN GUIA DE INSTALAÇÃO

K126MA



IT - Istruzioni originali

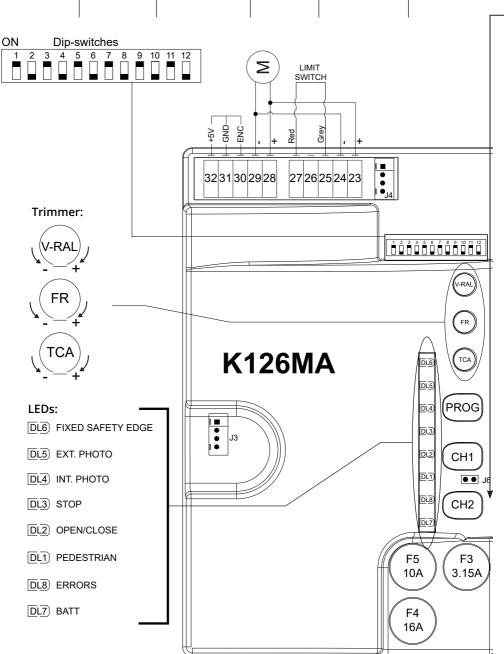






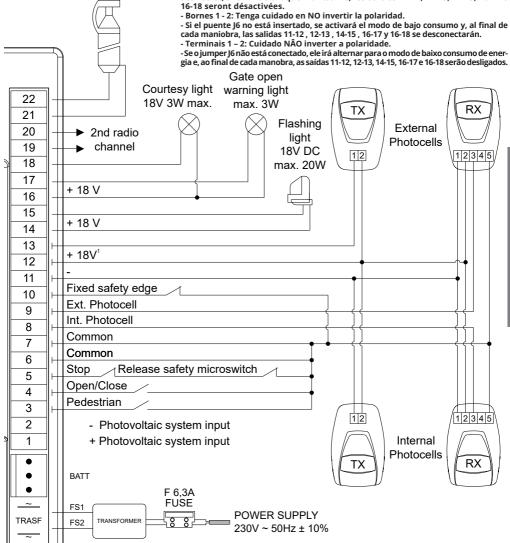


K126MA WIRING DIAGRAM SCHALTPLAN DER K126MA SCHÉMA CÂBLAGE K126MA ESQUEMA DEL CABLEADO K126MA ESQUEMA DE LIGAÇÕES K126MA





- Morsetti 1 2: Attenzione a NON invertire la polarità.
- Se il jumper J6 non è inserito, verrà attivata la modalità basso consumo e, al termine di ogni manovra, le uscite 11-12, 12-13, 14-15, 16-17 e 16-18 verranno spente.
 Terminals 1 2: Careful NOT to invert polarity.
- If Jumper J6 is not plugged in, energy saving mode will be activated and, at the end
 of each manouvre, outputs 11-12, 12-13, 14-15, 16-17 and 16-18 will be switched off.
 Klemmen 1 2: Achtung: Nicht verpolen.
- -Wenn der Jumper J6 nicht eingesteckt ist, wird die Modalität Energiespar aktiviert und am Ende jedes Manövers werden die Ausgänge 11-12, 12-13, 14-15, 16-17 und 16-18 abgeschaltet.
 - Etaux 1 - 2: Assurez-vous de NE PAS inverser la polarité.
- Si le cavalier J6 n'est pas inséré, la fonction modalité consommation réduite sera activée et, à la fin de chaque manœuvre, les sorties 11-12, 12-13, 14-15, 16-17 e



WARNINGS

This manual is designed to assist qualified installation personnel only. It contains no information that may be of interest to final users. This manual is enclosed with control unit K126MA and may therefore not be used for different products!

Important warnings:

Disconnect the mains power supply to the board before accessing it.

The K126MA control unit has been designed to control an electromechanical gear motor for automating gates and doors of all kinds.

Any other use is considered improper and is consequently forbidden by current laws.

Please note that the automation system you are going to install is classified as "machine construction" and therefore is included in the application of European directive 2006/42/EC (Machinery Directive). This directive includes the following prescriptions:

- Only trained and qualified personnel should install the equipment;
- the installer must first make a "risk analysis" of the machine;
- the equipment must be installed in a correct and workmanlike manner in compliance with all the standards concerned;
- after installation, the machine owner must be given the "declaration of conformity".

This product may only be installed and serviced by qualified personnel in compliance with current, laws, regulations and directives.

When designing its products, TAU observes all applicable standards (please see the attached declaration of conformity) but it is of paramount importance that installers strictly observe the same standards when installing the system.

Unqualified personnel or those who are unaware of the standards applicable to the "automatic gates and doors" category may not install systems under any circumstances.

Whoever ignores such standards shall be held responsible for any damage caused by the system! Do not install the unit before you have read all the instructions.

INSTALLATION

Before proceeding, make sure the mechanical components work correctly. Check that the gate slides freely on a horizontal plane (gates that open / close on sloping floors can affect the operation and duration of the control unit and the gearmotor).

Then make sure that the power consumption of the gear motor is not greater than 3A (otherwise the control panel may not work properly). Havig followed the previous points, now make sure the motor has a proper absorption. The K126 board starting from V5.17 release integrates a function to verify the absorption on the complete gate journey (Check paragraph ABSORPTION CHECK FUNCTION).

THE EQUIPMENT MUST BE INSTALLED "EXPERTLY" BY QUALIFIED PERSONNEL AS REQUIRED BY LAW. Note: it is compulsory to earth the system and to observe the safety regulations that are in force in each country.

IF THESE ABOVE INSTRUCTIONS ARE NOT FOLLOWED IT COULD PREJUDICE THE PROPER WORKING ORDER OF THE EQUIPMENT AND CREATE HAZARDOUS SITUATIONS FOR PEOPLE. FOR THIS REASON THE "MANUFACTURER" DECLINES ALL RESPONSIBILITY FOR ANY MALFUNCTIONING AND DAMAGES THUS RESULTING.

1. CONTROL PANEL FOR ONE 18/24V MOTOR WITH ENCODER

- ABSORPTION CHECK FUNCTION
- STATUS OF INPUTS SIGNALLED BY LEDs
- INCORPORATED FLASHING CIRCUIT
- ENCODER SENSOR FOR SELF-LEARNING OF TRAVEL
- 433.92 MHz 3 CHANNEL BUILT-IN RADIO RECEIVER (CH)
- BATTERY CHARGER BOARD (INTEGRATED)
- DIAGNOSTICS OF MALFUNCTIONS SIGNALLED BY LED
- POSSIBILITY OF ENERGY SAVING OPERATION

ATTENTION:

- do not use single cables (with one single wire), ex. telephone cables, in order to avoid breakdowns of the line and false contacts:
- do not re-use old pre-existing cables;
- In case of long sections of cables (> 20 m) for N.O./N.C. controls (e.g. OPEN / CLOSE, STOP, PEDE-STRIAN, etc.), in order to avoid gate malfunctions, it will be necessary to uncouple the various controls using RELAYS or using our 750T-RELE device.

2. INTRODUCTION

The K126MA board has two working modes, selectable through the J6 jumper (see wiring diagram).

J6 Jumped: standard mode, i.e. the control unit is powered all the time;

J6 Not jumped: low consumption mode, at the end of each maneuver the board automatically switches OFF itself and all the auxiliary devices connected. The board will automatically switch

OFF itself and all the auxiliary devices connected. The board will automatically switch ON again activating the OP/CL contact or pressing the remote (mode where power is supplied by other energy sources, ex. batteries charged by a photovoltaic panel).

Once the connection is achieved, in low-energy mode, press the PROG button briefly:

- All the green LEDs must be on (each of them corresponds to a Normally Closed input). The go off only when the controls to which they are associated are operated.
- All the red LEDs must be off (each of them corresponds to a Normally Open input). The light up
 only when the controls to which they are associated are operated.

3. TECHNICAL CHARACTERISTICS

| Board power supply | 230 V AC - 50 Hz |
|---|-------------------------------------|
| Max. absorption DC motor | 14 Ah - 18V DC 10,5 Ah - 24 V DC |
| Fast acting fuse for protection of input power supply 13,5V AC (F4 - 5x20) | F 16A |
| Fast acting fuse for battery charger protection (F5 - 5x20) | F 10A |
| Fast acting fuse for protection of auxiliary circuits 18V ² DC (F3 - 5x20) | F 3.15A |
| Motor power supply circuits voltage | 18V ² DC |
| Auxiliary device circuits supply voltage | 18V ² DC |
| Logic circuits supply voltages | 5V DC |
| Operating temperature | -20 °C ÷ +55 °C |

¹ 18V DC for MASTER18OR and T-ONE10B

Terminals Eunstion

4. CONNECTIONS TO TERMINAL BOARD

Description

| reminiais runction | Description |
|--------------------|--|
| FS1 - FS2 POWER S | - 13,5V AC control unit power supply input (18V DC for MASTER18QR and T-ONE10B). - 18V AC control unit power supply input (24VDC for MASTER-R and T-ONE8BR) Fed by the toroidal transformer and protected by the fuses (F 6,3A) on the 230V AC power supply. |

² 24VDC for MASTER-R and T-ONE8BR

| 1 - 2 | AUX INPUT | external power input (ex. Photovoltaic system 12V DC). NB: In the latest versions of the control boards, the voltage change through jumper J7 is no longer necessary (make sure whether it is present on the control board or not). ATTENTION: POWERING THE CONTROL UNIT WITH AN EXTERNAL SOURCE, ALL THE OTHER 18V (24V for MASTER-R) DC OUTPUTS BECOME THE SAME AS THE OUTSIDE VOLTAGE. |
|-------------|------------------------|--|
| 3 - 6 | PEDESTRIAN | N.O. input for PEDESTRIAN button - Controls prtial opening and closing (1/3 of the complete journey) and it is subject to the setting of DIP SW 2 and 4. $(3=PED-6=COM)$ |
| 4 - 6 | OPEN/CLOSE | OPEN/CLOSE button N.O. input – Controls the opening and closing of the automation and is regulated based on the function of dip-switches 2 and 4. ($4=O/C-6=COM$) |
| 5 - 6 | STOP | STOP button N.C. input – Stops the automation in any position, temporarily preventing the automatic closure, if programmed. (5= STOP - 6= COM) NOTE: A safety micro-switch is connected to the STOP push-button. In case the STOP input remains open for more than 5 seconds, the operator will perform a cycle at a slow speed to reset the operating parameters to the values originally saved (see "Restoring automatic operation"). The micro-switch should be connected in series to further STOP push-buttons where present. |
| 7 - 8 | INTERNAL PHOTOCELLS | PHOTOCELL OR SAFETY DEVICE input INSIDE the gate (Normally Closed contact). When these devices trigger during the opening phase, they temporarily stop the gate until the obstacle has been removed; during the closing phase they stop the gate and then totally open it again. Bridge the connectors if not used. (7= COM - 8= CLOSE) |
| 7-9 | EXTERNAL PHOTOCELLS | PHOTOCELL OR SAFETY DEVICE input OUTSIDE the gate (Normally Closed contact). Then these devices trigger during the closing phase, they stop the gate and then totally open it again. Bridge the connectors if not used. (7= COM - 9= FOT) Note: the photocell transmitter must always be supplied by terminals no. 12 and no. 13, since the safety system test (phototest) is carried out on it. Without this connection, the control unit does not work. To override the testing of the safety system, or when the photocells are not used, set dip-switch no. 6 to OFF. |
| 7 - 10 | SENSITIVE EDGE | SAFETY EDGE input (Resistive sensitive edge or with n.c. contact - see DIP SWITCH 12). It works during the opening phase and also during the closing phase, resulting in the temporary stop of the automation and: - the partial inversion of its movement for 20 cm (only in the opening phase) - the complete opening (only in the closing phase); thus freeing any obstacle. NOTE: if a resistive sensitive edge is connected, set dip-switch no. 12 to ON; If a fixed safety edge with NC contact is connected, set dip-switch no. 12 to OFF; Jumper terminals if not used. (7= COMMON - 10= SENSITIVE EDGE) |
| 11 - 12 ** | PHOTOCELLS | output 18V¹ DC max. 15 W per photocells (TX/RX) and auxiliaries (11 = NEGATIVE - 12 = POSITIVE) |
| 12 - 13 ** | TX PHOTOCELLS | output for the $18V^1DC$ transmitter photocell with the possibility of carrying out the phototest (with DIP 6 ON). (12= POSITIVE - 13= NEGATIVE) |
| 14 - 15 ** | FLASHING LIGHT | $18V^{\dagger}$ DC max. 20W output for flashing light supply, flashing signal supplied by the control unit, rapid for closing, slow for opening. (14= POSITIVE - 15= NEGATIVE) |
| 16 - 17* ** | GATE OPEN LIGHT | Output for OPEN GATE LIGHT 18V¹ DC, 3 W max; while the bar opens the light flashes slowly, when the bar is open it stays on and while closing it flashes at twice the speed. (16= POSITIVE - 17= NEGATIVE) |

| 16 - 18* ** | COURTESY LIGHT | 18V¹ AC, 15 W Output for auxiliary courtesy light. It comes on with the control pulse and stays ON until after the manoeuvre for a time settable through T-WIFI (default = 2 sec.) (16=POSITIVE - 18= NEGATIVE) |
|--------------|---------------------------|--|
| 19 - 20* | 2 nd CH RADIO | 2 nd radio channel output - for control of an additional automation or for switching on lights, etc (N.O. clean contact) Warning: to connect other devices to the 2nd Radio Channel (area lighting, pumps, etc.), use an additional auxiliary relay (see note at end of paragraph). WARNING: the default outlet is active monostable 2 sec. To switch it to active bistable or to modify the activation time it is necessary to use the T-WIFI (see relative instructions). |
| 21 - 22 | AERIAL | plug-in radio-receiver aerial input , for 433.92 MHz receivers only. (21= GROUND - 22= SIGNAL) |
| 23 - 24 | MOTOR (M2) | motor (M2) supply output 18V DC max. 300 VA. (23= POSITIVE - 24= NEGATIVE) See note below. |
| 25 - 27 | OPTIONAL LIMI SWITCHES | ⁷ Optional limit switches input: 25 - gray cable; 27 - red cable. |
| 26 | | Not in use |
| 28 - 29 | MOTOR (M1) | motor (M1) supply output 18V DC max. 300 VA. (28= POSITIVE - 29= NEGATIVE) |
| 30 - 31 - 32 | ENCODER (M1) | encoder supply and input (30= WHITE signal - 31= BLUE negative - 32= BROWN positive) |
| J3 | MEMORY CARD | Quick plug-in for MEMORY CARD connection for transmitters codes. |
| J4 | AUX | Quick coupling for the connection of the T-WIFI and T-CONNECT devices |
| | · | |

^{1 24}V for MASTER-R and T-ONE8BR

** If Jumper 6 is not plugged in, energy saving mode will be activated and, at the end of each manouvre, outputs 11-12, 12-13, 14-15, 16-17 and 16-18 will be switched off.



The terminal board for motor 2 (23-24) is to be used in support of the one for motor 1 (MASTER18QR / MASTER-R), or in case of fault/failure of the one for motor 1 (28-32), see wiring diagram page 2-3.

IMPORTANT:

- do not power up auxiliary relays o other devices through the 18V output (24V for MASTER-R) DC output (terminals 11 – 12) to avoid malfunctions of the control unit. Use separated power supply / transformers instead;
- do not connect switching feeders or similar apparatus close to the automation that may be a source of disturbance.

5. LOGIC ADJUSTMENTS

Make the logic adjustments.

Note: when any adjusting devices (trimmers or dip-switches) on the control panel are operated, a complete manoeuvre must be carried out in order for the new settings to take effect.

^{*} The outlets can be configured using the T-WIFI (see relative instructions). The standard configuration is shown in the table.

V-RAL adjusts the automation deceleration speed during the final section of the stroke;



Note: When memorizing the stroke, set the TRIMMER V-RAL fully turned counterclockwise (minimum deceleration speed).



RAL

FR. obstacle detection sensitivity adjustment.



Note: by rotating the TRIMMER FR. clockwise the sensitivity of the gearmotor to obstacles diminishes and therefore the thrust force increases; vice-versa, by rotating it counter-clockwise, the sensitivity of the gearmotor to obstacles increases and therefore the thrust force diminishes.

TCA +

T.C.A. Automatic Closing time adjustment: from about 1 to 120 seconds (see dip-switch no. 1);

Dip switch

| 1 | AUTOMATIC CLOSING | On | when completely open, closure is automatic after the set time on the T.C.A. trimmer has past. |
|---------|---------------------------|--------|---|
| | CLOSING | Off | the closing manoeuvre requires a manual command. |
| | | On | when the automation is operating, a sequence of opening/closing commands causes the automation to OPEN-CLOSE-OPEN-CLOSE, etc. |
| 2 2/457 | 2 / 4 STROKE | Off | in the same conditions, the same sequence of commands causes the automation to OPEN-STOP-CLOSE-STOP-OPEN-STOP, etc. (step-by step function) (see also dip switch 4). |
| 3 | CLOSES AGAIN AFTER THE | On | after the photocell is activated (input 7 - 9), the automation closes automatically after 5 seconds. |
| | PHOTOCELL | Off | function off. |
| 4 | NO REVERSE | On | the automation ignores the closure command during opening and auto-close time |
| | | Off | the automation responds as established by dip switch No. 2. |
| _ | PRE- | On | the pre-flashing function is enabled. |
| 5 | FLASHING | Off | the pre-flashing function is disabled. |
| | | On | the "photocell test" function is enabled. |
| 6 | 6 FOTOTEST | | the "photocell test" function is disabled. Note: to be used when the photocells are not used. |
| 7 | MASTER/ | On | enables the MASTER mode in the master/slave configuration (see T-COMM instructions). |
| | SLAVE | Off | enables the standard operation (single motor) or SLAVE mode in the master/slave configuration (see T-COMM instructions). |
| 8 | OPTIONAL LIMIT SV | VITCHE | ES (CABLES 25 - 27) |
| | NOT CONNECTED | . On | once the mechanical stop of the closing maneuver is reached, the automation makes a slight movement in the opposite direction to avoid jamming between the rack and the pinion. |
| | | Off | function deactivated |
| | CONNECTED | On | operation for gate with opening to the left (gearmotor side); |
| | CONNECTED | Off | operation for gate with opening to the right (gearmotor side); |
| | · | | |



To change the position of Dip 8, the power must be disconnected. Once modified, rerun the SetUp of the stroke

| Dip 9 | Dip 10 | Dip 11 | Automation | |
|-------|--------|--------|--|--|
| Off | Off | Off | T-ONE10B For gates up to 400 kg | |
| On | Off | Off | T-ONE10B For gates from 600 to 1000 kg | |
| Off | On | Off | T-ONE8BR (24v) | |
| On | On | Off | MASTER-R (24V Opening speed = Closing speed) | |
| Off | Off | On | MASTER18QR | |
| On | Off | On | MASTER-R (24V) | |
| Off | On | On | T-ONE8BR (24V Opening speed = Closing speed) | |
| On | On | On | CANTILEVER TONE10B (heavy) | |



IMPORTANT: In case the automation type change, a new setting of the dips # 9, 10 and 11 will be required. Before the new setup, however, it is necessary to proceed to a HARD RESET (see pag. 25) of the controller.

| SENSITIVE | On | RESISTIVE SENSITIVE EDGE (terminal No. 10). | |
|-----------|------|---|---|
| 12 | EDGE | Off | NC CONTACT SENSITIVE EDGE (terminal No. 10). Note: if not used, keep the DIP in the OFF position. |

6. MEMORIZATION PROCEDURE OF THE STROKE

WARNING: After powering the control panel, wait 2 seconds before you start performing the adjustment operations and check:

- The Input connections: all green LEDs DL6, DL5, DL4 and DL3 must be on steady.
- The mechanical stops of the automation must be installed and adjusted both in opening and in closing [see motor instructions].
- the position of dip-switches 9, 10 and 11. Dip-switches must be set according to the automation model (see table of dip-switches 9-10-11, "Logic adjustments" section).



IMPORTANT: Carry out the first stroke memorization with the RAL trimmer positioned fully turned counterclockwise (minimum deceleration speed).

-If the gate fails to move forward during the stroke memorization procedure, it is possible to increase the speed using the CH1 (= - minus) and CH2 (= + increase) keys. To adjust the speed, briefly press the buttons. N.B.: The speed changes made during this phase using the CH1 and CH2 keys are not permanent (valid only to memorize the stroke).

Remember to decrease the speed through CH1 during the closing/opening stop phase as there is a risk that the gate will slam the mechanical stop.

PROCEDURE WITHOUT LIMIT SWITCHES INSTALLED:

1. Start the procedure with the gate at approx. 0.5 m from the mechanical opening stop.



If the automation closes instead of opening, stop the run of the gate (by cutting the photocells or closing the STOP contact), invert the polarity of the motor, take the gate at approx 0,5 m from the mechanical stop) and restart the procedure from the beginning.

Make sure you don't stand near the automation during saving.

- 2. Press without releasing the PROG button (6 sec. ca.) till the DL8 LED starts flashing (yellow):
- 3. The automation starts to open slowly in search of the opening stop;
- 4. Once the opening stop is reached, the automation slowly starts closing in search of the closing stop;
- 5. Choice of the deceleration point in opening:
- The automation will start to open quickly, press therefore the PROG key to start the deceleration phase in opening at the selected point.
- (If it is not pressed, in any case the automation slows down starting from a minimum safety distance to prevent the gate from banging hard when opening).

6. Choice of the deceleration point in closing:

- After a short pause the automation will begin to close quickly, press therefore the PROG key to start the deceleration phase in closing at the selected point.

(If it is not pressed, in any case the automation slows down starting from a minimum distance of safety to prevent the gate from banging strongly when closing).

PROCEDURE WITH LIMIT SWITCHES INSTALLED:

1. Start the procedure with the gate at approx. 0.5 m from the opening limit switch.

If the automation closes instead of opening:

1. stop the gate stroke (through photocells or by pressing the STOP key)



- 2. remove the power supply to the electronic board and reverse the direction of the gate using the DIP SWITCH n. 8 $\,$
- 3. Before to restore the power to the electronic board, attend 10 seconds 4. repeat the programming by pressing the PROG key (6 sec. ca.) until the aut
- 4. repeat the programming by pressing the PROG key (6 sec. ca.) until the automation starts to open
- 2. Press without releasing the PROG button (6 sec. ca.) till the DL8 LED starts flashing (yellow):
- 3. The automation starts to open slowly in search of the opening limit switch;
- **4.** Once the opening limit switch has been reached, the automation slowly begins to close in search of the closing limit switch;

5. Choice of the deceleration point in opening:

- The automation will start to open quickly, press therefore the PROG key to start the deceleration phase in opening at the selected point.

(If it is not pressed, in any case the automation slows down starting from a minimum safety distance to prevent the gate from banging hard when opening).

6. Choice of the deceleration point in closing:

- After a short pause the automation will begin to close quickly, press therefore the PROG key to start the deceleration phase in closing at the selected point.

(If it is not pressed, in any case the automation slows down starting from a minimum distance of safety to prevent the gate from banging strongly when closing).

- HOW TO CHANGE THE DECELERATION POINTS

If you want to change the deceleration start points, just press again briefly (1 sec.) the PROG key (**only with closed automation**) and the automation will start to open again and will allow you to insert the new deceleration point in opening and closing by pressing the PROG key again in the desired points. Now the PROG key performs only the stroke update function

WARNING:

 During the memorization, the intervention of the safety devices (photocells, sensitive edge or stop input) stop the automation and pause the procedure itself; to resume, it will be necessary to press only and exclusively the PROG button.



Please remember that an obstacle during saving is interpreted as a mechanical limit stop (the system does not start any safety operation, it just stops the motor)

7. K126MA CHARACTERISTICS

TIMER-OPERATED OPENING AND CLOSING CYCLES

The opening/closing of the automation can be controlled by means of a timer that has a free N.O. output contact (relay). The timer must be connected to terminals 4 - 6 (OPEN/CLOSE button) and can be programmed so that, at the desired opening time, the relay contact closes until the desired closing time (when the timer's relay contact opens, enabling the automatic closing of the gate).

Note: the automatic closing function must be enabled by setting Dip-switch no. 1 to ON).

BATTERY CHARGER BOARD (INTEGRATED)

If the battery is connected the automation will operate in any case if there is no mains power supply. If the voltage drops below 11.3 Vdc, the automation ceases to operate (the control unit remains fed);

whereas, when the voltage drops below 10.2 Vdc, the card completely disconnects the battery (the control panel is no longer fed). During battery operation, LOW CONSUMPTION MODE will be automatically activated. At the end of each maneuver 11-12, 12-13, 14-15, 16-17 and 16-18 will be powered off. In order to connect the battery to the control board, it is required a specific connector supplied along with the battery.

Note: when the battery-mode is activated the system switches in low-power mode therefore the auxiliary outputs (11-12) are disabled. (For use of external receivers, Gsm, etc. connect these in parallel to the battery).

OBSTACLE DETECTION

If the obstacle detection function (adjustable through FR trimmer) is activated during an opening manoeuvre, the gate closes approx. 20 cm., if it is activated during a closing manoeuvre, the gate opens all the way.



WARNING: the control panel logics may interpret mechanical friction as an obstacle.

8. DIAGNOSTICS LED

| DL1 - Red | PEDESTRIAN button LED signal |
|-------------|--------------------------------|
| DL2 - Red | OPEN/CLOSE button LED signal |
| DL3 - Green | STOP button LED signal |
| DL4 - Green | INTERNAL PHOTOCELLS LED signal |
| DL5 - Green | EXTERNAL PHOTOCELLS LED signal |
| DL6 - Green | SENSITIVE EDGE LED signal |

LED - DL7

Apart from highlighting the presence of the battery, LED DL7 displays any mistakes with a series of pre-set flashes in various colours:

| Key: | led always on; | 0 | led flashing; |
|-------------------------------------|------------------------|---------|---|
| always on | (green): | fully-c | harged battery, main voltage present; |
| always on | (yellow): | batter | y charging; |
| 1 flash eve | ery 4 seconds (green): | fully-c | harged battery, no main voltage; |
| | | Check | the main voltage; |
| 0 1 flash every 4 seconds (yellow): | | | r supply through photovoltaic panel (terminals 1-2), ry charger disabled |
| 0 1 flash eve | ery 2 seconds (red): | low ba | attery; |
| | | Charge | the battery, replace the battery; |
| ofast flashi | ng (red): | faulty | battery; |
| | | Replac | e the battery; |
| | | | |

LED - DL8

The DL8 LED indicates mistakes in the board logic with a series of pre-set flashes in different colours: *Key:* led always on; led flashing;

• 1 flash every 4 seconds (green): **normal operation**;

| ○ / ○ alternate flashing: (red/green) saving to be performed; | | |
|---|--|--|
| alternate fast flashing ✓ / ○ : (green/yellow) | Update stroke – deceleration points; | |
| | See the section "HOW TO CHANGE THE DECELERATION POINTS" in paragraph 6 | |
| o fast (yellow) flashing: | saving in progress; | |

| 1 (red) flash: | phototest error |
|-----------------------|---|
| | Disable phototest (dip-switch 6 OFF), check the operation of the photocells and their connection; |
| 0 1 (yellow) flash: | unknown status, next operation REALIGNMENT; |
| 2 (red) flashes: | obstacle for motor 1; |
| | Make sure there are no obstacles across the path of the gate and that it slides smoothly; |
| | With an active automatic closing feature, after the intervention meant to detect the obstacle, the automatic closing is deactivated. A command pulse is required to carry out the closing; |
| O 3 (red) flashes: | no motor 1 encoder signal; |
| | Check wiring, check encoder by TEST-ENCODER (optional); |
| 4 (red) flashes: | no motor 1 signal; |
| | Check wiring, check the motor rotates freely and is powered directly by the battery, check fuse F5; |
| o 5 (red) flashes: | max current limit for motor 1 exceeded; |
| | Excessive absorption peaks of the gearmotor, check there are no obstacles on the automation path, check the current absorption of the motor when in a no-load condition and when applied to the gate, |
| o 6 flashes: | master/slave communication error; |
| (yellow) | Check wiring between the controllers, efficiency of slave controller (fuses), efficiency of interface boards; |
| o 7 flashes (red): | Sensitive edge safety intervention |
| | A command pulse is required to carry out the closure; |
| 0 8 (red) flashes: | Eeprom external memory fault; |
| | Replace the external memory module; |
| 0 8 (yellow) flashes: | Eeprom data error (internal/external); |
| | Perform procedure RADIO MEMORY RESET; |

Apart from the logic mistakes, the DL8 LED indicates also the status of the control unit during the saving of the radio controls.

| channel CH1 waiting to be saved; |
|--|
| CH1 channel memory full; |
| channel CH2 waiting to be saved; |
| CH2 channel memory full; |
| channel CH3 waiting to be saved; |
| CH3 channel memory full; |
| |
| CH1 channel waiting to be cancelled; |
| cancelling of channel CH1 in progress; |
| CH2 channel waiting to be cancelled; |
| cancelling of channel CH2 in progress; |
| CH3 channel waiting to be cancelled; |
| cancelling of channel CH3 in progress; |
| |

When LEDs DL7 and DL8 flash at the same time they indicate:

| flashing • + • (red + red): | factory reset procedure waiting for confirmation; | |
|-----------------------------------|---|--|
| flashing • + • (yellow + yellow): | waiting for total cancellation of the radio channels; | |

Multiple errors are signalled by a 2-second pause between signals.

Should the encoder (obstacle detection) activates while closing, the controller will reverse the direction and slowly open until the laef reaches its fully opened position. Auto Close function will be deactivated until a further command pulse is given. In case of 5 consecutive safety interventions the controller will progressively increase the Auto Close delay. Once the closing has been successfully achieved, the Auto Close delay will go back to standard setting.

9. ABSORPTION CHECK FUNCTION (from 5.17 release onwards)

This function allows to monitor the absorption during a complete cycle in order to value the motor stress. To activate this function press and hold for 2 seconds simultaneously CH1, PROG, CH2 and them start the motor (OP/CL contact, remote, PROG button).







The absorption registered is shown according to the following diagram:

| 1 0 | 0 0 | |
|-------------------|----------|----------|
| Level | DL7 | DL8 |
| Easy to move gate | O(Off) | O(Off) |
| | (Green) | O(Off) |
| | (Green) | (Green) |
| | (Green) | (Yellow) |
| | (Yellow) | (Green) |
| | (Yellow) | (Yellow) |
| | (Yellow) | (Red) |
| | (Red) | (Yellow) |
| Hard to move gate | • (Red) | (Red) |

After 5 minutes from the function activation, the board automatically resumes to the standard LED visualization (to resume manually press simultaneously CH1, PROG and CH2).

10. RESTORING AUTOMATIC OPERATION

Should the Bar need to be operated manually, use the release system. After the manual operation:

after a Mains Power Failure, such as a black-out (controller remains disconnected for a certain time)
or after a manual release (without power shortage to the controller for more than 5 seconds), the
automation will be moving slowly to allow the Controller to establish its Limits (REALIGNMENT
procedure).

11. 433.92 MHz BUILT-IN RADIO RECEIVER

The radio receiver can learn up to a maximum of 30 codes of rolling code (S2RP, S4RP, K-SLIM-RP, T-4RP) to be set freely on 3 channels.

The first channel directly commands the control board for opening the automatic device; the second channel commands a relay for a N.O. no-voltage output contact (terminals 19 - 20, max. 24V AC, 1 A)

and the third channel controls directly the pedestrian opening from the controller.

LEARNING SYSTEM FOR RADIO CONTROL DEVICES

CH1 = 1st channel (OPEN/CLOSE) CH2 = 2nd channel CH3 = 3rd channel (PEDESTRIAN)

- 1 Press button CH1 briefly to associate a radio control device with the OPEN/CLOSE function;
- 2 the (green) DL8 LED is ON to indicate the code learning mode has been activated (if no code is entered within 10 seconds the board exits the programming function):
- 3_ press the button of the relative radio control device:
- the (green) DL8 LED turns off to indicate saving is complete and then on again immediately waiting for other radio control devices (if this is not the case, try to re-transmit or wait 10 seconds and 4 the (green) DL8 LED turns off to indicate saving is complete and then on again immediately waitrestart from point 1);
- 5 to memorise codes to other radio control devices, press the key to be stored on other devices within 2-3 sec. After this time (DL8 LED turns off) must repeat the procedure from point 1 (up to a maximum of 30 transmitters):
- 6 if you wish to save on the 2nd channel, repeat the procedure from point 1 using the CH2 key instead of CH1 (in this case the DL8 LED is yellow);
- 7 to program transmitters into the third channel, repeat procedure from point 1 using CH1 and CH2 buttons at the same time (DL8 will turn on red);
- 8 to exit the learning mode without memorising a code, press button CH1 or CH2 briefly.



If the maximum number of radio controls is reached (30), the LED DL8 will begin to flash rapidly for about 3 seconds but without performing memorisation.

REMOTE PROGRAMMING BY MEANS OF T-4RP / K-SLIM-RP / S-2RP / S-4RP (V 4.X)

With the new version of software V 4.X it is possible to carry out the remote self-learning of the new version of transmitters T-4RP / K-SLIM-RP / S-2RP / S-4RP (V 4.X), that is without pressing the receiver's programming buttons.

It will be sufficient to have an already programmed transmitter in the receiver in order to start the procedure of remote programming of the new transmitters. Follow the procedure written on the instructions of the transmitter T-4RP / K-SLIM-RP / S-2RP / S-4RP (V 4.X).

CANCELLING CODES FROM RADIO CONTROL DEVICES

- 1 Keep button CH1 pressed for 3 seconds in order to cancel all the associated radio control devices;
- 2 LED DL8 flashes slowly to indicate that the cancellation mode has been activated;
- 3_ press button CH1 again for 3 seconds:
- 4 LED DL8 turns off for approx. 3 seconds and then remains steady to indicate that the code has been cancelled:
- 5 repeat the procedure from point 1 using button CH2 to cancel all the associated radio control de-
- 6 repeat procedure from point 1 using CH1 and CH2 buttons at the same time to erase all transmitters programmed into the third channel;
- 7 to exit the learning mode without memorising a code, press button CH1 or CH2 briefly.

MEMORY CAPACITY

The code memory capacity* can be expanded from 30 to 126, 254 or 1022 codes (transmitters) by replacing the memory cards as follows (plug them onto J3 connector, see wiring diagram):

126 codes Art. 250SM126 254 codes 250SM254 Art. 1022 codes Art. 250SM1022

To allow the previously stored codes (max. 30) to be moved to the control unit, it is required to install a memory card, making sure that the control unit is at that time off and that the memory card is brand new and therefore completely empty.

When the control unit is restarted, the codes will automatically move to the memory card.

Moving the codes from the control unit to the memory card does not work if on the memory card used, radio control codes have already been stored and the memory card has been subsequently erased. To insert new radio controls, the operation described above shall be repeated.

^{*} Control units are supplied with a standard built-in 30-code memory. The memory card for enhancing the code memory capacity must be ordered separately.



WARNING: Control unit must be turned OFF to insert / remove a memory card.

RADIO MEMORY RESET:

 press without releasing keys CH1 and PROG till LEDs DL7 and DL8 start flashing quickly with a yellow light. At this point release the keys and press them again till the LEDs go off confirming the operation is complete (if they are not pressed the board reverts to normal operation after about 12 seconds).

HARD RESET (factory setting):

- press without releasing keys CH2 and PROG till LEDs DL7 and DL8 start flashing quickly with a red light. At this point release the keys and press them again till the LEDs go off (reset in progress), confirming the operation is complete (if they are not pressed the board reverts to normal operation after about 12 seconds); When the unit starts again saving will be required.



In case of Hard Reset the memory of the radio receiver will not be erased: all existing transmitters remain programmed.

12. SET-UP FOR OPERATION WITH TAU APPS

In order to use the TauApp and TauOpen apps, it will be necessary to connect to input J4 of the K126MA control unit using the supplied cable, the respective T-WIFI and T-CONNECT devices. To activate the operation of the apps see the respective instructions.

13. MALFUNCTIONS: POSSIBLE CAUSES AND SOLUTION

The automation does not start

- a- Check there is 230V AC power supply with the multimeter.
- b- Check, in the standard mode, that the NC contacts on the board are really normally closed (4 green LEDs on).
- c- Set dip-switch 6 (phototest) OFF.
- d- Increase the FR trimmer to the limit.
- e- Check that the fuses are intact with the multimeter.

The radio control has very little range

- a- Check that the ground and the aerial signal connections have not been inverted.
- b- Do not make joints to increase the length of the aerial wire.
- c- Do not install the aerial in a low position or behind walls or pillars.
- d- Check the state of the radio control batteries.

The gate opens the wrong way

Invert the motor connections on the terminal block, terminals 28 - 29 and terminals 23 - 24 (if used).

14. GUARANTEE: GENERAL CONDITIONS

TAU guarantees this product for a period of 24 months from the date of purchase (as proved by the sales document, receipt or invoice).

This guarantee covers the repair or replacement at TAU's expense (ex-works TAU: packing and transport at the customer's expense) of parts that TAU recognises as being faulty as regards workmanship or materials.

For visits to the customer's facilities, also during the guarantee period, a "Call-out fee" will be charged for travelling expenses and labour costs.

The guarantee does not cover the following cases:

- If the fault was caused by an installation that was not performed according to the instructions
 provided by the company inside the product pack.
- If original TAU spare parts were not used to install the product.
- If the damage was caused by an Act of God, tampering, overvoltage, incorrect power supply,

- improper repairs, incorrect installation, or other reasons that do not depend on TAU.
- If a specialised maintenance man does not carry out routine maintenance operations according to the instructions provided by the company inside the product pack.
- Wear of components.

The repair or replacement of pieces under guarantee does not extend the guarantee period. In case of industrial, professional or similar use, this warranty is valid for 12 months.